## Minnel

## CALIBRATOR PRODUCER

## SERVICE MANUAL VOLTAGE AND CURRENT CALIBRATOR TYPE INMEL 10



Przedsiębiorstwo Wdrożeniowe INMEL Sp. z o. o.
ul. Sulechowska 1
65-950 Zielona Góra
POLAND
tel. (68) 32953 31, tel. /fax (68) 3243260
www.inmel.com.pl, e-mail: inmel@inmel.com.pl
serwis@inmel.com.pl

## TABLE OF CONTENTS

Chapter 1. TECHNICAL DESCRIPTION ..... 1-1
1.1. Technical parameter of INMEL10 calibrator. ..... 1-1
1.2. General specifications ..... 1-13
1.3. Programmatic functions ..... 1-14
Chapter 2. WORKING INSTRUCTION ..... 2-1
2.1. Preparation to work ..... 2-1
2.2. Description of the front panel ..... 2-2
2.3. Description of the rear panel ..... 2-3
2.4. Description of the control board ..... 2-4
2.5. Connecting load to calibartor. ..... 2-6
2.6. Programiming the calibrator. ..... 2-7
2.6.1. Generation of direct currents and voltages ..... 2-7
2.6.2. Generation of alternating currents and voltages. ..... 2-7
2.6.3. Entering output value limitation ..... 2-8
2.6.4. Modification of output quantity value by set deviation value ..... 2-8
2.6.5. Writing signal value into memory ..... 2-8
2.6.6. Writing value sequence into memory ..... 2-8
2.6.7. Memory read-out ..... 2-8
2.7. Exemplary meter check-out procedure ..... 2-9
2.8. Specification of errors indicated by the calibrator .....  2-9
Chapter 3. ACCESORIES ..... 3-1
Chapter 4. OPERATING RECOMMENDATIONS ..... 4-1

## 1. TECHNICAL DESCRIPTION

The INMEL 10 calibrator is a precision source of direct and alternating voltages and currents. It has been designed primarily for calibration and checking of measuring instruments. It finds another application in laboratory measurements as a precision power supply.

Its operational features are enhanced by a set of programmable functions which facilitate measurement procedures. Entering set values of programmed functions is handled by the operator who uses the keys in the control board retractable from the calibrator casing. The output and feedback terminals are on the front panel.

### 1.1. Technical parameters of calibrator INMEL 10

Specifications have been tabulated in tables 1.1.1.-1.1.6.

Tabl. 1.1.1. Direct voltages ranges parameters.

| Parameter | Range |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1000 V | 100 V | 10 V | 1 V | 100 mV | 10 mV |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| Useable setting range | $\begin{aligned} & 0 \ldots \\ & +1099.999 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0 \ldots \\ & +109.9999 \mathrm{~V} \end{aligned}$ | $0 \ldots$ <br> $\pm 10.99999 \mathrm{~V}$ | 0... <br> $\pm 1.099999 \mathrm{~V}$ | $0 .$. <br> $\pm 109.9999 \mathrm{mV}$ | 0... <br> $\pm 10.99999 \mathrm{mV}$ |
| Resolution | $1000 \mu \mathrm{~V}$ | $100 \mu \mathrm{~V}$ | $10 \mu \mathrm{~V}$ | $1 \mu \mathrm{~V}$ | $0.1 \mu \mathrm{~V}$ | $0.01 \mu \mathrm{~V}$ |
| Basic error | $\pm 0.03 \%$ setting $\pm 0.004 \%$ range |  |  | $\begin{aligned} & \pm 0.02 \% \\ & \text { setting } \\ & \pm 0.004 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & \pm 0.05 \% \text { setting } \\ & \pm 10 \mu \mathrm{~V} \end{aligned}$ |  |
| Operating error ${ }^{2)}$ | $\pm 0.05 \%$ setting $\pm 0.007 \%$ range |  |  | $\begin{aligned} & \pm 0.03 \% \\ & \text { setting } \\ & \pm 0.007 \% \\ & \text { range } \\ & \hline \end{aligned}$ | $\begin{aligned} & \pm 0.07 \% \text { setting } \\ & \pm 16 \mu \mathrm{~V} \end{aligned}$ |  |
| $\begin{aligned} & 15 \text { minutes } \\ & \text { drift. }{ }^{3)} \end{aligned}$ | $\begin{aligned} & \pm 0.002 \% \text { setting } \\ & \pm 0.001 \% \text { range } \\ & \hline \end{aligned}$ |  | $\pm 0.001 \%$ range |  | $\pm 3 \mu \mathrm{~V}$ |  |
| $7 \mathrm{~h} \mathrm{drift}{ }^{3}$ | $\begin{aligned} & \pm 0.01 \% \text { setting } \\ & \pm 0.005 \% \text { range } \\ & \hline \end{aligned}$ |  | $\begin{aligned} & \pm 0.005 \% \text { setting } \\ & \pm 0.001 \% \text { range } \end{aligned}$ |  | $\pm 0.01 \%$ range $\pm 10 \mu \mathrm{~V}$ |  |


| Parameter | Range |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1000 V | 100 V | 10 V | 1 V | 100 mV | 10 mV |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| Additional error caused by change: - ambient temperature | $\pm 0.03 \%$ setting $\pm 0.004 \%$ range |  |  | $\begin{aligned} & \pm 0.02 \% \\ & \text { setting } \pm \\ & 0.004 \% \\ & \text { range } \\ & \hline \end{aligned}$ | $\pm 0.04 \%$ setting $\pm 10 \mu \mathrm{~V}$ |  |
| - supply voltage | $\pm 0.006 \%$ setting $\pm 0.0008 \%$ range |  |  | $\begin{aligned} & \pm 0.004 \% \\ & \text { setting } \\ & \pm 0.0008 \% \\ & \text { range } \\ & \hline \end{aligned}$ | $\pm 0.01 \%$ setting $\pm 2 \mu \mathrm{~V}$ |  |
| - load current | $\pm 0.002 \%$ range |  |  |  | caused by output resistance of $0,1 \Omega$ |  |
| - load reactance | $\pm 0.001 \%$ range |  |  |  |  |  |
| Linearity error | $\pm 0.01 \%$ range |  |  |  |  |  |
| PARD ${ }^{4)}$ | $\begin{aligned} & \hline 0.15 \% \text { setting } \\ & +0.03 \% \text { range } \\ & \hline \end{aligned}$ |  | $\begin{array}{r} \hline 0.03 \% \\ \text { range } \\ \hline \end{array}$ | $\begin{aligned} & \hline 0.1 \% \text { setting } \\ & +0.1 \% \text { range } \end{aligned}$ | $0.1 \%$ setting $+10 \mu \mathrm{~V}$ |  |
| Common <br> mode <br> rejection <br> ratio ${ }^{6}$ <br> within <br> frequency <br> $0 \ldots . .50 \mathrm{~Hz}$ | 80 dB | 90 dB |  | 100 dB | 110 dB |  |
| $\begin{array}{\|l} \begin{array}{l} \text { Short- } \\ \text { circuit } \\ \text { current } \end{array} \\ \hline \end{array}$ | 50 mA |  | 1.8 A |  | 1 A | 100 mA |


| Parameter | Range |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1000 V | 100 V | 10 V | 1 V | 100 mV | 10 mV |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| Transition process caused by the change: ${ }^{2)}$ | transition process time/transition process amplitude ${ }^{7)}$ |  |  |  |  |  |
| - supply voltage | 0.1 s / 1\% range |  |  |  |  |  |
| - set value | $7 \mathrm{~s} / 1 \%$ range $^{8)}$ |  |  | $4 \mathrm{~s} / 1 \%$ range |  |  |
| - polarity | - |  |  | $6 \mathrm{~s} / 1 \%$ range |  |  |
| - range | $10 \mathrm{~s} / 10 \%$ range |  |  |  |  |  |
| $\begin{aligned} & \text { - load } \\ & \left.0 \mathrm{~A} \rightarrow \max ^{5}\right) \\ & \max \rightarrow 0 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & \hline 6 \mathrm{~s} \mathrm{1} \mathrm{\%} \\ & \text { range } \\ & 100 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & \hline 6 \mathrm{~s} 1 \% \\ & \text { range } \\ & 200 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & \hline 3 \mathrm{~s} \mathrm{1} \mathrm{\%} \\ & \text { range } \\ & 50 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & \hline 3 \mathrm{~s} \mathrm{1} \mathrm{\%} \\ & \text { range } \\ & 150 \% \\ & \text { range } \end{aligned}$ | 0.1 s $1 \%$ range |  |

1) in reference conditions according to table 1.1.5. within 12 months,

2 ) in rated operating conditions according to table 1.1.5.,
3) after 1 h pre-heating time,
4) rms value of AC component in the $2 \mathrm{~Hz} . . .10 \mathrm{kHz}$,
5) maximum load current in rated operating conditions,
6) the ratio of common-mode voltage (external source voltage generated between insulated output terminals of the calibrator and the casing screen or earthing terminals)to the change of the output quantity value caused by the common-mode voltage, expressed in decibels,
7) the difference between the top or bottom output value in the transition process and the steady-state output value,
8) for setting greater than $0.1 \%$ range

Tabl. 1.1.2. Alternating voltage range specifications.

| Parameter | Range |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1000 V | 100 V | 10 V | 1 V | 100 mV | 10 mV |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| Usable setting range | 10... <br> 1099.999 V | 1... <br> 109.9999 V | 0.1... <br> 10.99999 V | 0.01... <br> 1.099999 V | 1... <br> 109.9999 mV | $\begin{aligned} & 0.1 \ldots \\ & 10.99999 \mathrm{mV} \end{aligned}$ |
| Resolution | $1000 \mu \mathrm{~V}$ | $100 \mu \mathrm{~V}$ | $10 \mu \mathrm{~V}$ | $1 \mu \mathrm{~V}$ | $0.1 \mu \mathrm{~V}$ | $0.01 \mu \mathrm{~V}$ |
| Basic error | $\begin{aligned} & \pm 0.05 \% \text { setting } \pm 0,01 \% \text { range } \pm 50 \mu \mathrm{~V}^{9)} \\ & \pm 0.1 \% \text { setting } \pm 0.02 \% \text { range } \pm 100 \mu \mathrm{~V} \end{aligned}$ |  |  |  | $\begin{aligned} & \pm 0.2 \% \text { setting } \pm 50 \mu \mathrm{~V}^{9)} \\ & \pm 0.4 \% \text { setting } \pm 100 \mu \mathrm{~V} \end{aligned}$ |  |
| Operating error ${ }^{2)}$ | $\begin{aligned} & \pm 0.08 \% \text { setting } \pm 0.02 \% \text { range } \pm 75 \mu \mathrm{~V}^{9} \\ & \pm 0.13 \% \text { setting } \pm 0.025 \% \text { range } \pm 128 \mu \mathrm{~V} \end{aligned}$ |  |  |  | $\begin{aligned} & \pm 0.24 \% \text { setting } \pm 65 \mu \mathrm{~V}^{9} \\ & \pm 0.48 \% \text { setting } \pm 120 \mu \mathrm{~V} \end{aligned}$ |  |
| 15 minutes drift ${ }^{3)}$ | $\pm 0.005 \%$ setting $\pm 0.002 \%$ range |  |  |  | $\pm 10 \mu \mathrm{~V}$ |  |
| $7 \mathrm{~h} \mathrm{drift}{ }^{3)}$ | $\pm 0.02 \%$ setting $\pm 0.005 \%$ range |  |  |  | $\pm 0.02 \%$ range $\pm 20 \mu \mathrm{~V}$ |  |
| Additional <br> error ${ }^{2}$ <br> caused by <br> the change: <br> - ambient <br> temperatu <br> re <br> - supply <br> voltage <br> - load <br> current <br> - load <br> reactance <br> Lia |  |  |  |  |  |  |
|  | $\pm 0.05 \%$ setting $\pm 0.01 \%$ range $\pm 50 \mu \mathrm{~V}$ |  |  |  | $\pm 0.04 \%$ setting $\pm 10 \mu \mathrm{~V}$ |  |
|  | $\pm 0.01 \%$ setting $\pm 0.002 \%$ range $\pm 10 \mu \mathrm{~V}$ |  |  |  |  |  |
|  | $\begin{aligned} & \pm 0.02 \% \text { setting } \pm 0.003 \% \text { range }{ }^{9)} \\ & \pm 0.04 \% \text { setting } \pm 0.006 \% \text { range } \end{aligned}$ |  |  |  | limited by output resistance $0,1 \Omega$ |  |
|  | $\pm 0.001 \%$ range |  |  |  |  |  |
| Linearity error | $\pm 0.01 \%$ range |  |  |  |  |  |



| Parameter | Range |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1000 V | 100 V | 10 V | 1 V | 100 mV | 10 mV |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| Transition process caused by the change of: | transition process time/transition process amplitude ${ }^{8)}$ |  |  |  |  |  |
| - supply voltage | $0.1 \mathrm{~s} / 1 \%$ range |  |  |  |  |  |
| - setting | $7 \mathrm{~s} / 5 \%$ range |  |  |  |  |  |
| - range | 10 s / 10\% range |  |  |  |  |  |
| - output <br> value frequency | $1.5 \mathrm{~s} / 20 \%$ range |  |  |  |  |  |
| $\underset{\max \rightarrow 0 \mathrm{~A}}{-\mathrm{load}}$ | $\begin{aligned} & 6 \mathrm{~s} \mathrm{5} \mathrm{\%} \\ & \text { range } \\ & 100 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & \hline 6 \text { s 5\% } \\ & \text { range } \\ & 200 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & \hline 5 \mathrm{~s} 5 \% \\ & \text { range } \\ & 50 \% \\ & \text { range } \end{aligned}$ | $\begin{aligned} & 5 \mathrm{~s} \mathrm{5} \mathrm{\%} \\ & \text { range } \\ & 150 \% \\ & \text { range } \end{aligned}$ | 0.1 s 1\% range |  |

1) in reference conditions according to table 1.1.5. within 12 months,

2 ) in rated operating conditions according to table 1.1.5.,
3) after pre-heating for 1 h ,
4) in rated operating conditions in the $2 \mathrm{~Hz} . . .200 \mathrm{kHz}$ band,
5) the lower THD coefficient pertains to voltages lower than 800 V ,
6) maximum load current at rated operating conditions,
7) the ratio of common-mode voltage (external source voltage generated between insulated output terminals of the calibrator and the casing, screen or earthing terminals) to the change of the calibrator and the caused by the common-mode voltage, expressed in decibels,
8) the difference between the top or bottom output value in the transition process and the steady-state output value,
9) the higher value for frequency over 500 Hz .

Tabl. 1.1.3. Direct current specifications.

| Parameter | Range |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10 A | 1 A | 100 mA | 10 mA | 1 mA |
| 1 | 2 | 3 | 4 | 5 | 6 |
| Usable setting range | 0... 10.99999 A | 0... $\pm 1.099999 \mathrm{~A}$ | 0... $\pm 109.9999 \mathrm{~mA}$ | $\begin{aligned} & 0 \ldots \\ & \pm 10.99999 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0 \ldots \\ & \pm 1.099999 \mathrm{~mA} \end{aligned}$ |
| Resolution | $10 \mu \mathrm{~A}$ | $1 \mu \mathrm{~A}$ | 100 nA | 10 nA | 1 nA |
| Basic error ${ }^{1)}$ | $\begin{aligned} & \pm 0.04 \text { \% set. } \\ & \pm 0.01 \% \text { rang. } \end{aligned}$ | $\pm 0.03 \%$ setting $\pm 0.005 \%$ range |  |  | $\begin{gathered} \pm 0.03 \% \text { set. } \\ \pm 0.01 \% \\ \text { range } \\ \hline \end{gathered}$ |
| Operating error ${ }^{2)}$ | $\begin{aligned} & \pm 0.07 \% \text { set. } \\ & \pm 0.02 \% \text { rang. } \end{aligned}$ | $\begin{gathered} \pm 0.05 \% \text { set. } \\ \pm 0.015 \% \text { rang. } \end{gathered}$ | $\begin{aligned} & \pm 0.05 \% \text { setting } \\ & \pm 0.009 \% \text { range } \end{aligned}$ |  | $\begin{gathered} \pm 0.05 \% \text { set. } \\ \pm 0.02 \% \\ \text { range } \\ \hline \end{gathered}$ |
| $\begin{array}{\|l} \hline \begin{array}{l} 15 \text { minute } \\ \text { drifft }^{3} \end{array} \\ \hline \end{array}$ | $\pm 0.005 \%$ set. | $\pm 0.002 \%$ range |  |  |  |
| $7 \mathrm{~h} \mathrm{drift}{ }^{3}$ | $\begin{aligned} & \pm 0.02 \% \text { set. } \\ & \pm 0.005 \% \text { rang. } \end{aligned}$ | $\begin{aligned} & \pm 0.005 \% \text { set. } \\ & \pm 0.005 \% \text { rang. } \end{aligned}$ | $\pm 0.005 \%$ setting $\pm 0.005 \%$ range |  |  |
| Additional error caused by the change: - ambient temperature |  |  |  |  |  |
|  | $\begin{aligned} & \pm 0.04 \% \text { set. } \\ & \pm 0.01 \% \text { rang. } \end{aligned}$ | $\pm 0.03 \%$ setting $\pm 0.005 \%$ range |  |  | $\begin{aligned} & \pm 0.03 \% \text { set. } \\ & \pm 0.01 \% \\ & \text { range } \\ & \hline \end{aligned}$ |
| - supply voltage | $\begin{aligned} & \pm 0.008 \% \text { set. } \\ & \pm 0.002 \% \text { rang. } \end{aligned}$ | $\pm 0.006 \%$ setting $\pm 0.001 \%$ range |  |  | $\begin{aligned} & \pm 0.006 \% \text { set } \\ & \pm 0.002 \% \text { rang } \end{aligned}$ |
| - load voltage | $\begin{aligned} & \pm 0.01 \% \text { set } \\ & \pm 0.01 \% \text { rang. } \end{aligned}$ | $\pm 0.01 \%$ <br> rang. | $\pm 0.002 \%$ range |  | $\pm 0.01 \% \text { range }$ |
| - load reactance | $\pm 0.002 \%$ rang. | $\pm 0.001 \%$ range |  |  | $\pm 0.01 \%$ rang. |
| Linearity error | $\pm 0.01 \%$ range |  |  |  |  |
| PARD ${ }^{5)}$ | $\begin{aligned} & 0.2 \% \text { setting } \\ & +0.05 \mathrm{mV} / \mathrm{Ro} \end{aligned}$ | $0.1 \%$ setting + $0.5 \mathrm{mV} / \mathrm{Ro}$ |  |  | $\begin{aligned} & 0.1 \% \text { setting } \\ & +\mathrm{mV} \end{aligned}$ |
| Common mode rejection ratio $^{7}$ in the frequency $0 . . .50 \mathrm{~Hz}$ | 100 dB | 90 dB |  |  |  |


| Parameter | Range |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10 A | 1 A | 100 mA | 10 mA | 1 mA |
| 1 | 2 | 3 | 4 | 5 | 6 |
| Open circuit voltage | 8 V | 25 V |  |  |  |
| Transition <br> process <br> caused by the <br> change : <br> - supply <br> voltage <br> - setting <br> - polarity <br> - range <br> - load <br> $0.1 \mathrm{~V} \rightarrow \max { }^{6}$ <br> $\max \rightarrow 0.1 \mathrm{~V}$ | transition process time/transition process amplitude ${ }^{7)}$ |  |  |  |  |
|  | 0.1 s / 1\% range |  |  |  |  |
|  | $\begin{aligned} & \hline 7 \mathrm{~s} / 1 \% \\ & \text { range }^{9)} \end{aligned}$ | $4 \mathrm{~s} / 1 \%$ range |  |  |  |
|  | - | $6 \mathrm{~s} / 1 \%$ range |  |  |  |
|  | $10 \mathrm{~s} / 10 \%$ range |  |  |  |  |
|  | $\begin{array}{\|l} \hline 5 \mathrm{~s} / 1 \% \\ \text { range. } \\ 5 \mathrm{~s} / 12 \mathrm{~A}-\mathrm{I}_{\mathrm{n}} \\ \hline \end{array}$ | $\begin{aligned} & 6 \mathrm{~s} / 1 \% \text { range } \\ & 6 \mathrm{~s} / 220 \% \text { ran. } \end{aligned}$ | $\begin{aligned} & 6 \mathrm{~s} / 1 \% \text { range } \\ & 6 \mathrm{~s} / 300 \% \text { range } \end{aligned}$ |  |  |

1) in reference conditions according to table 1.1.5. within 12 months,
2) in rated operating conditions according to table 1.1.5.
3) after 1 h pre-heating time,
4) for setting over 0.1 mA ,
5) rms value of AC component in the band $2 \mathrm{~Hz} . . .10 \mathrm{kHz}$, Ro-load resistance,
6) maximum load voltage at rated operating conditions,
7) the ratio of common-mode voltage (external source voltage generated between insulated output terminals of the calibrator and the casing, screen or earthing terminals) to the change of the output quantity value caused by the common-mode voltage, expressed in decibels,
8) the differences between the top and the bottom output value in the transition process and the steady-state output value,
9) for setting over $0.1 \%$ range.

Tabl. 1.1.4. Alternating current range specifications.

| Parameter | Range |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10 A | 1 A | 100 mA | 10 mA | 1 mA |
| 1 | 2 | 3 | 4 | 5 | 6 |
| Usable setting range | $\begin{aligned} & 0.1 \ldots 10.99999 \\ & \text { A } \\ & \hline \end{aligned}$ | $\begin{aligned} & 0.01 \ldots 1.09999 \\ & 9 \mathrm{~A} \\ & \hline \end{aligned}$ | $\begin{aligned} & 1 \ldots 109.9999 \\ & \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.1 \ldots 10.99999 \\ & \mathrm{~mA} \\ & \hline \end{aligned}$ | $\begin{aligned} & 0.01 \ldots 1.09999 \\ & 9 \mathrm{~mA} \\ & \hline \end{aligned}$ |
| Resolution | $10 \mu \mathrm{~A}$ | $1 \mu \mathrm{~A}$ | 100 nA | 10 nA | 1 nA |
| Basic error) | $\begin{aligned} & \pm 0.05 \% \text { setting } \pm 0.01 \% \text { range } \pm 2 \mu \mathrm{~A}^{\text {8) }} \text { 12) } \\ & \pm 0.1 \% \text { setting } \pm 0.02 \% \text { range } \pm 4 \mu \mathrm{~A} \end{aligned}$ |  |  |  |  |
| Operating error) | $8)$ $\pm 0.085 \%$ set. $\pm 0.04 \%$ rang. $\pm 0.13 \%$ set. $\pm 0.045 \%$ rang. | $\begin{aligned} & \pm 0.085 \% \text { set } \\ & \pm 0.13 \% \text { setti } \end{aligned}$ | $\begin{gathered} 8) \\ \text { ting } \pm 0.03 \% \\ \text { ing } \pm 0.055 \% \end{gathered}$ | $\begin{aligned} & \text { nge } \pm 3.5 \mu \mathrm{~A} \\ & \text { nge } \pm 5.1 \mu \mathrm{~A} \end{aligned}$ | 8 8) $\pm 0.08 \%$ set. $\pm 3.8 \mu \mathrm{~A}$ $\pm 0.13 \%$ set. $\pm 6.5 \mu \mathrm{~A} \quad$ 12) |
| $\begin{aligned} & 15 \text { minutes } \\ & \text { drift. }{ }^{3} \text { ) } \end{aligned}$ | $\begin{gathered} \pm 0.01 \% \text { set. } \\ \pm 0.002 \% \text { rang. } \end{gathered}$ | $\pm 0.005 \%$ setting $\pm 0.001 \%$ range |  |  |  |
| $7 \mathrm{~h} \mathrm{drift}{ }^{3}$ | $\begin{gathered} \pm 0.03 \% \text { set. } \\ \pm 0.01 \% \text { rang. } \end{gathered}$ | $\pm 0.02 \%$ setting $\pm 0.005 \%$ range |  |  |  |
| Additional error caused by the change: <br> - ambient temperature <br> - power supply <br> - load voltage <br> - load reactance |  |  |  |  |  |
|  | $\pm 0.05 \%$ setting $\pm 0.01 \%$ range $\pm 2 \mu \mathrm{~A}$ |  |  |  |  |
|  | $\pm 0.01 \%$ setting $\pm 0.002 \%$ range $\pm 0.4 \mu \mathrm{~A}$ |  |  |  |  |
|  | $\begin{aligned} & \pm 0.01 \% \text { set. } \\ & \pm 0.01 \% \text { rang. } \end{aligned}$ | $\begin{aligned} & \pm 0.02 \% \\ & \pm 0.04 \% \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { setting } \pm 0.02 \\ & \text { setting } \pm 0.04 \\ & \hline \end{aligned}$ | $\begin{aligned} & 6 \text { range }{ }^{8)} \\ & \text { range } \\ & \hline \end{aligned}$ | $\begin{aligned} & \pm 0.15 \% \text { range. }{ }^{8} \\ & \pm 0.3 \% \text { range. }{ }^{9} \end{aligned}$ |
|  | $\begin{array}{\|l\|} \hline \pm 0.001 \% \text { rangeC } \\ \pm 0.03 \% \text { rangeL } \end{array}$ | $\begin{aligned} & \pm 0.001 \% \text { range (C) }{ }^{10} \\ & \pm 0.01 \% \text { range }(\mathrm{L}) \\ & \hline \end{aligned}$ |  |  |  |
| Linearity error | $\pm 0.01 \%$ range |  |  |  |  |


| Parameter | Range |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10 A | 1 A | 100 mA | 10 mA | 1 mA |
| 1 | 2 | 3 | 4 | 5 | 6 |
| Total harmonic distortion coefficient in the frequency band $40.00 \ldots . .48 .00 \mathrm{~Hz}$ | 1.7\% setting | $\begin{aligned} & 0.4 \% \text { setting + } \\ & 2 \mathrm{mV} / \mathrm{Ro} \end{aligned}$ | $0.2 \%$ setting $+1.5 \mathrm{mV} / \mathrm{Ro}$ |  | $\begin{aligned} & 0.3 \% \text { setting } \\ & + \text { mV/Ro } \end{aligned}$ |
| $48.01 \ldots . .4999 .9 \mathrm{~Hz}$ | 0.8\% setting |  | $0.2 \%$ setting + $2 \mathrm{mV} / \mathrm{Ro}$ |  | $\begin{aligned} & 0.3 \% \text { setting } \\ & +6 \mathrm{mV} / \mathrm{Ro} \end{aligned}$ |
| $500.0 . . .2000 \mathrm{~Hz}$ | 1\% setting |  | 0.3\% setting + $2 \mathrm{mV} / \mathrm{Ro}$ |  | $\begin{aligned} & 0.3 \% \text { setting } \\ & +8 \mathrm{mV} / \mathrm{Ro} \end{aligned}$ |
| 2001...4999Hz | 2\% setting |  | 0.4\% setting + $5 \mathrm{mV} / \mathrm{Ro}$ |  | $\begin{aligned} & 0.5 \% \text { setting } \\ & +8 \mathrm{mV} / \mathrm{Ro} \end{aligned}$ |
| Common <br> mode <br> rejection ratio <br> in the <br> frequency <br> range of <br> $0 \ldots . .50 \mathrm{~Hz}$ | 100 dB | 90 dB |  |  |  |
| Open circuit voltage | 5 V | 25 V |  |  |  |
| Transition process caused by the change of: | transition process time / transition process amplitude ${ }^{7}$ ) |  |  |  |  |
| - supply voltage | $0.1 \mathrm{~s} / 1 \%$ range |  |  |  |  |
| - setting | $7 \mathrm{~s} / 5 \%$ range |  |  |  |  |
| - range | 10 s / $10 \%$ range |  |  |  |  |
| - frequency of the output quantity | $\begin{aligned} & 1.5 \mathrm{~s} / 20 \% \\ & \text { range } \end{aligned}$ | 1.5 s / 20\% range |  |  |  |
| $\begin{aligned} & - \text { load } \\ & 0,1 \mathrm{~V} \rightarrow \max \\ & \max ^{5} \rightarrow 0,1 \mathrm{~V} \\ & \hline \end{aligned}$ | $\left\lvert\, \begin{aligned} & 5 \mathrm{~s} / 5 \% \text { rang. } \\ & 5 \mathrm{~s} / 12 \mathrm{~A}-\mathrm{I}_{\mathrm{n}} \end{aligned}\right.$ | $\begin{aligned} & 6 \mathrm{~s} / 5 \% \text { rang. } \\ & 6 \mathrm{~s} / 220 \% \text { rang } \end{aligned}$ | $\begin{aligned} & 6 \mathrm{~s} / 5 \% \text { range } \\ & 6 \mathrm{~s} / 300 \% \text { range } \\ & \hline \end{aligned}$ |  |  |

1) in reference conditions according to table 1.1.5. within 12 months,
2) in rated operating conditions according to table 1.2.5.
3) after 1 h pre-heating time,
4) in rated operating conditions within the frequency band of $2 \mathrm{~Hz} . .200 \mathrm{kHz}$,
5) maximum load voltage in rated operating conditions,
6) the ratio of common-mode voltage ( external source voltage generated between insulated output terminals of the calibrator and casing, screen or earthing terminals) to the change of the output quantity value caused by the common-mode voltage, expressed in decibels,
7) the difference between the top and bottom output value in the transition process and the steady-state output value,
8) higher value for frequency over 500 Hz ,
9) for settings over 0.1 mA ,
10) L - inductive load, C - capacity load,
11) Ro - load resistance,
12) for the 1 mA range at frequency above 2000 Hz aditionally $1 \%$ setting.
13) for 10 A range valid for setting $0.1 \ldots 5 \mathrm{~A}$ in all frequency range, for setting above 5 A for frequency $\leq 2000 \mathrm{~Hz}$.

Tabl. 1.1.5. Reference conditions and rated operating conditions.

| Influential quantity or influential factor | Reference quantity or reference range | Rated usability range |
| :---: | :---: | :---: |
| 1 | 2 | 3 |
| Ambient temperature | $+23^{\circ} \mathrm{C} \pm 2^{\circ} \mathrm{C}$ | $+5 \ldots+40^{\circ} \mathrm{C}$ |
| Atmospheric pressure |  | 6 kPa |
| Relative humidity |  | $80 \%$ |
| Supply voltage | $230 /$ | $\mathrm{V} \pm 10 \%$ |
| Supply voltage frequency | $50 /$ | $\mathrm{z} \pm 5 \%$ |
| Supply voltage shape | sinus | $\beta \leq 0.05$ |
| Preheating time | not less | 30 minutes |
| Load resistance or load current or load voltage for range: | over $1 \mathrm{M} \Omega$ over $100 \mathrm{k} \Omega$ over $0.1 \mathrm{k} \Omega$ over $100 \mathrm{k} \Omega$ $\begin{gathered} 1 \mathrm{k} \Omega \pm 50 \% \\ 100 \Omega \pm 50 \% \\ 10 \Omega \pm 50 \% \\ 1 \Omega \pm 50 \% \\ 0.1 \Omega \pm 50 \% \\ \hline \end{gathered}$ | fig. 1.2.1. <br> fig. 1.2.2. <br> 0...1.1 A <br> defined by output resistance $\begin{gathered} 0.1 \Omega \\ 0 \ldots .11 \mathrm{~V} \\ 0 \ldots .11 \mathrm{~V} \\ 0 \ldots .11 \mathrm{~V} \\ 0 . .11 \mathrm{~V} \end{gathered}$ <br> fig. 1.2.3. |
| load reactance | zero | $\begin{aligned} & \hline 0 \ldots 10 \mathrm{nF}^{1)} \\ & 0 \ldots . .10 \mathrm{mH} \end{aligned}$ |
| Alternating currents and voltage frequency | 40... $4999 \mathrm{~Hz}^{2)}$ |  |
| Position of calibrator | according with instruction $\pm 30^{\circ}$ |  |
| Air movement velocity | $0 . .0 .5 \mathrm{~m} / \mathrm{s}$ |  |
| Ventilation | free |  |
| Radio frequency interference | none /negligible/ |  |
| Vibration and shocks | none /negligible/ |  |
| Magnetic and electric fields | none/ Earth field/ |  |
| Insolation | none |  |
| Content of sand, dust, salt, water and aggressive gases in air | none /negligible/ |  |

1) For the alternating voltages range the allowable load capacity is additionally limited by the current limitation threshold. Foe the alternating current range the allowable load inductance is additionally limited by the voltage limitation threshold. For the alternating voltage range the allowable load inductance is 2 mH for $\mathrm{f}_{\mathrm{N}}=100 \ldots . .4999 \mathrm{~Hz}$. For the alternating current range the allowable load inductance follows from the formula $\frac{100}{I_{N} / A / * f_{N} / H_{Z} /} / m H /$ for $\mathrm{I}_{\mathrm{N}}=0.1 \ldots 10.99999 \mathrm{~A}$ and $\mathrm{f}_{\mathrm{N}}=100 \ldots 4999 \mathrm{~Hz}$.
2) For currents over $5 \mathrm{~A}-40 \ldots 2000 \mathrm{~Hz}$.

Tabl. 1.1.6. Parameters of alternating voltages and currents output frequencies.

| Range | Setting range <br> $(\mathbf{H z})$ | Resolutions (Hz) | Error in rated operating <br> conditions |
| :---: | :---: | :---: | :---: |
| 100 Hz | $40 \ldots 99.9$ | 0.01 | $0.01 \%$ frequency range |
| 1 kHz | $100 \ldots 999.9$ | 0.1 | $0.01 \%$ frequency range |
| 5 kHz | $1000 \ldots . .2999$ | 1 | $0.02 \%$ frequency range <br> $0.05 \%$ frequency range |

### 1.2. General specifications

a) safety requirements class I acc. to IEC 1010-1
highest common-mode voltage: 100 V in frequency band $0 . . .50 \mathrm{~Hz}$ for low-voltage terminals, 1500 V in frequency band $0 . . .50 \mathrm{~Hz}$ for high-voltage terminals


Fig. 1.2.1. Current limitation threshold for 1000 V range
b) casing protection grade IP 20 acc. to PN-79/E-08106
c) design requirements acc. to PN-71/T-06500/03
d) mechanical requirements group I acc. to PN-75/T-06500/07
e) climatic requirements group I acc. to PN-75/T-06500/06
f) transport and storage acc. to PN-85/T-06500/08
g) power consumption $-150 \mathrm{~V} * \mathrm{~A}$
h) cassette dimensions:
width -430 mm
height - 360 mm
depth -350 mm
weight -25 kg
i) control board dimensions:
width -340 mm
height -50 mm
weight - 240 mm


Fig. 1.2.2. Current limitation threshold for 100 V range


Fig. 1.2.3. Voltage limitation threshold for 10A range

### 1.3. Programmatic functions

- work with automatic range change at exceeding the range value by $109.9999 \%$ or down $11 \%$ contractual value of range
- work in any selected range within the operational setting acc. to table 1.1.1... 1.1.4,
- entering the amplitude limitation of the output signal,
- increasing or decreasing of the output quantity amplitude by declared value,
- continuous increasing and decreasing of the output quantity amplitude at two various velocities,
- recording ten settings into ten memory cells,
- recording the following sequence of settings into memory cells:
$\frac{X W}{K} * 1 ; \frac{X W}{K} * 2 ; \ldots ; \frac{X W}{K} * K$
where:
$X W$ - setting value loaded XW memory $K-$ number of division points $1 \leq \mathrm{K} \leq 10$,
- calculation of error expressed in (\%)
in relation to the rated value: principal shown in the operational display) and contractual (loaded into the XW memory cell),
- read-out of storage cells,
- resetting the operational display,
- return to the initial state (resetting).


## 2. Working instruction

### 2.1. Preparation to work

The acclimatization time of the calibrator should be longer than 24 h . Follow the requirements in table 1.2.5. when selecting the assembly place for the unit. The supply wire should be plugged to a network outlet supplying alternating current of rated voltage $230 / 110 \mathrm{~V} / 50 / 60 \mathrm{~Hz}$ after previously connect joint of this wire to outlet in back part this device. The outlet should equipped with a nulling pin to ensure neutralization of the calibrator casing.

Before starting the calibrator slide the control board out of the casing. Upon pressing the „POWER" button ( fig. 2.2.1.) in the front panel, the control board display (fig.2.3.1.) shows the massage HELLO Simultaneously $\mathbf{0 m V} \pm \mathbf{4 0 \mu V}$ value is generate on the output terminals. After 5 ... 10 seconds the operational display dies out and the output display shows the setting ,$+ \mathbf{0 0 0 0 0 0}$ and lights up the unit $\mathbf{V}$. The preheating time after switching the calibrator on should not be shorter than 30 minutes. After such preheating the calibrator is ready for operation.

### 2.2. Description of the front panel



Fig. 2.2.1. View of the calibrator from the front panel.

Figure 2.2.1. shows front panel layout where the designators means

1. high output terminal for current and voltage range $1 \mathrm{~V}, 10 \mathrm{~V}$.
2. low output terminal for all ranges.
3. high output terminal for ranges 100 V i 1000 V .
4. high feedback terminal for ranges 1 V and 10 V and high output terminal for ranges 10 mV i 100 mV .
5. low feedback terminal for ranges 1 V i 10 V and low output terminal for ranges 10 mV i 100 mV .
6. high feedback terminal for ranges 100 V i 1000 V .
7. internal screen terminal.
8. „amplitude error exceeded" - indicator.
9. Signaling of switch on high voltages ranges 100 V i 1000 V .
10. 4 wires switch with signaling
11. power supply switch with signaling,

### 2.3. Description of the rear panel.



Fig. 2.3.1. View of the calibrator from the rear panel side.

Figure 2.3.1. shows rear panel layout where the designators means:

1. Power outlet.
2. Serial interface joint and code switch (DIP switch).
3. Console connection.

### 2.4. Description of the control board



Fig. 2.4.1. View of the control board

Fig. 2.4.1. shows control board layout where the designator mean:

1. operational display which can show

- the currently entered value,
- the read-out value from storage cell (item 2.6.7.),
- the value of calculated error $\boldsymbol{\delta}$ or $\boldsymbol{\varepsilon}$,
- signal frequency on output terminals in the case of operation on alternating voltages or currents (item 2.6.2.)
- programming error massage (item 2.8.1.)

2. output display; it shows value being generated on the output terminals,
3. the units of the quantities exposed in the operational display,
4. the units of the quantities exposed in the output display,
5. Signaling that read-out value from storage cell is parameter of alteranting signal,
6. Signaling that on output terminals is generating alternating signal,
7. Signaling that output amplitude limitation has been introduced,
8. signaling of interface control,
9. signaling of work in a constant selected range,
10. 0 ... 9 CE - numerical button which help to enter the value shown in the operational display, starting from the most significant item, with a coma after any item,
11. CE - resetting the operational display or return to the state before pressing the $\chi+\Delta$ or $x-4$ (item 2.6.4).
12. Hz mV VA A - selection of unit entered,
13. $\square, \square$ - selection of polarity of entered quantity,
14. STi - storing the operational display content into a storage cell (item 2.6.5.).
15. RCL - recall of storage cell content to the operational display (item 2.6.7.).
16. 니 - storing the output amplitude limitation value into the LIM memory cell.
17. $\Delta$ - storing the deviation value into the. $\Delta$ memory cell,
18. $x+\Delta x-\Delta$ - increase or decrease output value by set deviation value,
19. $X_{w}$ - storing the setting value to the $X_{w}$ memory cell,
20. $\delta$ - calculation and indication of error in relation to rated value.
The error is shown in the formula:
$\delta=\frac{X N-X R}{X N}$
where:
$X R$ - the value generated on the output terminals ,
$X N$ - the rated value corresponding to the value printed in the operational display or read out from a memory cell,
21. $\varepsilon$ - calculation and indication of error in relation to the selected value.
The error is shown in the formula:
$\varepsilon=\frac{X N-X R}{X W}$
where:
$X R$ - the value generated on the output terminals (exposed in the output display),
$X N$ - rated value corresponding to the value printed on the operational display or read out from memory cell,
$X W$ - selected value loaded into XW memory cell.
22. RLL - switching of calibrator control from the board (local) to interface (remote) or the other way round.
In the calibrator without interface pressing the button does not change the control mode.
23. $z$ - declaration of work on a selected range depending on the range number entered on the operational display .
24. $K$ - loading the number of division points into the memory cell K .
25. $\quad \square$ - infinitely variable increase and decrease 0.00001 of range,
26. \# \# - infinitely variable increase and decrease of output value with signal movement by 0.001 of range,
27. E - rewriting of operational monitor indications into the output monitor with simultaneous generation of the rewritten value on the output terminals.
28. C - resetting- return to the state after switching on ( 0 mV is generated on the output terminals).

| Number of range | Selected range value |
| :---: | :---: |
| 0 | 10 mV |
| 1 | 100 mV |
| 2 | 1 V |
| 3 | 10 V |
| 4 | 100 V |
| 5 | 1000 V |
| 6 | 1 mA |
| 7 | 10 mA |
| 8 | 100 mA |
| 9 | 1 A |
| 10 | 10 A |

### 2.5. Connection load to calibrator

The ways of load connecting (e.g. checked meter) to calibrator was shown on fig. 2.5.1.-2.5.6. The way connecting terminal „GUARD" to load shown on schemes, should treat as recommended by producer.

The following designation have been assumed in the drawings:
N - low terminal,
W - high terminal,
WN - high terminal of high voltage,
E - internal screen terminal.
The four-wire connection reduces the series resistance impact on the voltage on load terminals.

For milivolt range the output resistance is $0.1 \Omega$. In the case the load input impedance is higher than $10 \mathrm{k} \Omega$, the calibrator output resistance entails a negligible error. If the load input impedance is lower than $10 \mathrm{k} \Omega$, a correction may be taken into account.

The voltage on the calibrator output terminals is expressed in the formula:

$$
U_{w y}=U_{N} \frac{R_{o}}{0.1 \Omega+R_{o}}
$$

(2.5.1.)
where:
$U_{N}$ - setting defined in voltage units.
$R_{O}$ - load input resistance expressed in ohms


Fig. 2.5.1. Two-wire load connecting for current ranges.


Fig. 2.5.2. Two-wire load connecting 1 V and 10 V ranges.

INMEL 10


Fig. 2.5.3. Four-wire load connecting for 1 V and 10 V ranges

INMEL 10


Fig. 2.5.5. Four-wire connecting for 100 V and 1000 V ranges.

### 2.6. Programming the calibrator

The calibrator is programmed with the controls of the board (fig. 2.4.1.). A given value is printed with the digit keys (item. fig. 2.4.1.) and shown in the operational display.

### 2.6.1. Generation of direct currents and voltages.

Write setting value.
Write polarity sign $\square$ or $\square$.
Write the unit $m V, V, m A$.
Accept by key $E$ - which is tantamount to generation of set value on the output terminals

INMEL 10


Fig. 2.5.4. Two- wire load connecting for 100 V and 1000 V ranges.

INMEL 10


Fig. 2.5.6. Load connecting for 10 mV and 100 mV ranges.

### 2.6.2. Generatinon of alternating currents and voltages

Write frequency value.
Write unit Hz .
Accept by key E - which is tantamount to breakover to alternating current or voltage range indicated by AC diode.
The rms of the alternating signal equals the direct signal generated up to now.

### 2.6.3. Entering output value limitation.

Write in the limitataion value.
Write in unit mV , $\mathrm{mA}, \mathrm{A}$.
Accept by key 니․
Limitation entered is indicated with the LIM diode. Any attempt at writing on the output display of a signal value higher than the limitation value results in the message Err 08.

### 2.6.4. Modification of output quantity value by set deviation value.

Write in deviation value.
Write in unit $\mathrm{mV}, \mathrm{V}$; $\mathrm{mA}, \mathrm{A}$.
Accept by key $\triangle$.
Use the keys $x+\Delta, x-\Delta$ keys to call the written in deviation value. The latter will be shown on the operational display and will simultaneously modify the output value by the set deviation value which will entail a change in the output display.
Repeated pressing of the keys $\begin{aligned} X+\lambda \\ , ~ X-\lambda \\ \text { will }\end{aligned}$ result in multiple modification of the output value.
Pressing the CE will result in automatic return to the state before the first pressing of the $X+\Delta$ or $x-\Delta$.

### 2.6.5. Writing signal value into memeory.

Write in signal value.
Write in the polarity sign + or $\square$.
Write in the unit $\mathrm{mV}, \mathrm{V}$; $\mathrm{mA}, \mathrm{A}$.
Use the 5 T0 key to cell the programme of writting into memory 0 to 9 , which will automatically write the signal value to the indicate cell. If any other value had been stored in the same cell it will be reset and replaced with the new value.

In the case of storing the alternating parameters, the procedure has to be continued.
Write in the signal frequency value.
Write the unit Hz .
With the sTD key and the storage cell number write the frequency value into memory. This replace the formerly stored direct signal value with the alternating signal value.

### 2.6.6. Writing value sequence into memory.

Write in the maximum value of the sequence.
When working on direct ranges- write in the polarity sign $\square_{\square}$ or $\square$.
Write in the unit $m \mathrm{~V}, \mathrm{~V}, \mathrm{~mA}, \mathrm{~A}$.
Accept by key $\mathrm{X}_{\mathrm{w}}$.
Write in the number of division points fron 1 to 10 .
Accept by the key K
Upon pressing the $K$ key - values from the sequence will be written into the storage cells 0 to K-1
$\frac{X W}{K} * 1 ; \frac{X W}{K} * 2 ; \ldots ; \frac{X W}{K} * K$.

### 2.6.7. Memory read-out

Use the key to recall the memory readout procedure.
Depending on the type of memeory cell to be read-out you should:

- with 0 - 9, - keys call the memory cell into the operation display. If no value had been stored in the cell, the error Err 06 will be indicated.
If an alternating signal had been stored in the memory cell, such a signal will be indicated simultaneously (light AC).
Reapeated pressing of the key with the same cell number will result in showing the signal frequency value

Pressing a key of another number will result in showing a respective storage cell content in the operational display.

- Pressing the keys $x_{\mathrm{w}} \mathrm{K} \Delta \square \mathrm{Z}$ Hz will result in showing the following cells contents in the operational display
XW - selected value,
$\mathbf{K}$ - number of division points,
$\Delta$ - deviation value,
LIM - limitation value,
$\mathbf{Z}$ - number of range,
Hz - signal frequency generated on the output (when working on the alternating ranges).
If no value had been stored in the memeory cell, an error will be indicated (table 2.8.1.).


### 2.7. Examplary meter check-out procedure

Task: check wheter the basic error of the meter does not exceed 0.1 V on the 5 V range of alternating voltage.

The check has to be carried out at five points: $1 \mathrm{~V}, 2 \mathrm{~V}, 3 \mathrm{~V}, 4 \mathrm{~V}, 5 \mathrm{~V}$.

Tabl. 2.7.1.

| Procedure | State of monitors |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Operational and diodes |  | Output and diodes |  |
| 1 | 2 | 3 | 4 | 5 |
| 1) Proper calibrator (item.2.1.) or press the key C <br> 2) Declared work on 10 V range $\square$ 3 Z |  |  | $\begin{aligned} & .000000 \\ & .000000 \\ & .000000 \end{aligned}$ | $\begin{gathered} \mathrm{V} \\ \mathrm{~V} \\ \mathrm{~V}, \mathrm{Z} \end{gathered}$ |
| 3) Write in setting of value or frequency alternating signal (item.2.6.2.) <br> 0 $\square$ V5 | $\begin{gathered} 0.1 \\ 0.1 \\ - \\ 5 \\ 50 \\ 50 \\ 50.00 \end{gathered}$ | V <br> Hz <br> Hz | $\begin{gathered} .000000 \\ .000000 \\ 0.10000 \\ 010000 \\ 0.10000 \\ 0.10000 \\ 0.10000 \end{gathered}$ | $\begin{gathered} \mathrm{V}, \mathrm{Z} \\ \mathrm{~V}, \mathrm{Z} \\ \mathrm{~V}, \mathrm{Z} \\ \mathrm{~V}, \mathrm{Z} \\ \mathrm{~V}, \mathrm{Z} \\ \mathrm{~V}, \mathrm{Z} \\ \mathrm{AC}, \mathrm{Z}, \mathrm{~V} \end{gathered}$ |
| 4) Enter the output voltage limitation 5.2 V to prevent meter defects (item.2.6.3.) 5 <br> 5) Connect the meter to the output terminals acc.(item 2.5.1.) | $\begin{gathered} 5 \\ 5 \\ 5.2 \\ 5.2 \end{gathered}$ | V | $\begin{aligned} & 0.10000 \\ & 0.10000 \\ & 0.10000 \\ & 0.10000 \\ & 0.10000 \end{aligned}$ | $\begin{gathered} \mathrm{AC}, \mathrm{~V}, \mathrm{Z} \\ \mathrm{AC}, \mathrm{~V}, \mathrm{Z} \\ \mathrm{AC}, \mathrm{~V}, \mathrm{Z} \\ \mathrm{AC}, \mathrm{~V}, \mathrm{Z} \\ \mathrm{AC}, \mathrm{~V}, \mathrm{Z}, \mathrm{LIM} \end{gathered}$ |

Tabl. 2.7.1.



Tabl. 2.7.1.

| Procedure | State of monitors |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Operational and diodes |  | Output and diodes |  |
| 1 | 2 | 3 | 4 | 5 |
| 9) check whether the meter indications remain within the programmed error by changing the setting by set value of deviation $\langle X+\Delta>$ $\text { or <X- } \Delta>$ <br> If the meter pointer moves above 1 V on the scale, the meter remains within the allowable basic error limit. <br> additionally can: calculate error value for this point. In this case use increase keys and set pointer to the scale mark <br> Read out the rated value from the memory RCL <br> 1 $\square$ <br> Calculate the error $\delta$ | 0.10000 <br> 1.00000 <br> XXXXXX <br> error value | AC, V <br> \% | 0.10000 <br> 0.90000 <br> 1.00000 <br> 1.XX000 <br> 1.XXXX0 <br> 1.XXXX0 <br> 1.XXXX0 <br> 1.XXXX0 | AC, V, Z, LIM AC, V, Z, LIM <br> AC, V, Z, LIM <br> AC, V, Z, LIM <br> AC, V, Z, LIM <br> AC, V, Z, LIM <br> AC, V, Z, LIM <br> AC, V, Z, LIM |



Tabl. 2.7.1.

| Procedure | State of monitors |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Operational and diodes |  | Output and diodes |  |
| 1 | 2 | 3 | 4 | 5 |
| 10) repeat the procedures item $8-10$ for the remaining points RCL 2 $\square$ ROL 3 3 RCL 4 | $\begin{aligned} & 2.00000 \\ & 3.00000 \\ & 4.00000 \\ & 5.00000 \end{aligned}$ | AC, V <br> AC, V <br> AC, V <br> AC, V |  |  |

### 2.8. Specification of error indicated by the calibrator

The calibrator indicates:
faulty programming writing a message on the operational display Err + error number. Using the 3.8.1. chart you can the cause of the error.
Only two keys in the control board are accessible at that time: <CE> and <C>. The <CE> key reset the operational display and allows writing new data in, the <C> returns the calibrator to state just after the power was switched on (2.1.).

- overrun of amplitude error limit or distortion coefficient, caused by overload or opening of contact of the output and feedback terminals, is indicated with diodes in the calibrator front panel (item. 8 fig. 2.2.1.).

Return to normal working conditions automatically stops these indications..

Tabl. 2.8.1. Specification of programming errors..

| Err 01 | Exceed operation setting range, |
| :---: | :---: |
| Err 02 | Incompatibility of selected range unit with the unit of introduced setting, |
| Err 03 | Memory storage without entering the value or unit, |
| Err 04 | Erroneous sequence of pressing the keys, |
| Err 06 | No data in the storage cell or input incomplete (e.g. polarity sign not specified), |
| Err 07 | No division point K given in the storage cell, |
| Err 08 | Limitation value LIM overrun, |
| Err 09 | No data in the memory cells $\Delta$, LIM, XW, |
| Err 10 | Erroneous range selection, |
| Err 11 | Incompatibility of the unit of generated value and the unit of deviation or lack of date in the deviation memory when pressing the $\mathrm{X} \pm \Delta$ keys, |
| Err 12 | Wrong number of division K, |
| Err 15 | Incompatibility of units: XW value, generated value, rated value. |
| Err 16 | No polarity sign for rated or maximum value when calculating the $\delta$, or $\varepsilon$, |
| Err 17 | No XW value when calculated the $\delta$ error, |
| Err 19 | $\delta$ error or $\varepsilon$ error calculated value overrun over $100 \%$. |

## 3. ACCESSORIES

Warranty certificate
1 pc.
Service Manual
Spare fuse
1 pc.
2 pcs.

## 4. OPERATING RECOMMENDATIONS

When using the INMEL 10 calibrator as a precision source of direct or alternating voltages and currents in calibration and checking of measuring instruments you should take into account the transition processes which occur when changing the range or the settings of voltage, current and frequency. The quantities of the transition states, i.e. the response time and the transition amplitude have been presented in table. 1.2.1., 1.2.2., 1.2.3. i 1.2.4. of Service Manual.

The following recommendations have to be adhered to in order to minimize the quantities of transition processes:

1. Declare operation on constant range. Working on constant range you avoid overshoots following from the change of range.
2. Load termination and disconnection to the calibrator should be affected on settings close to zero for voltage ranges and precisely zero for ranges.
If you terminate load to the calibrator at the time the voltage of 500 V or higher is generated it may interfere with the work of the microprocessor controller, e.g. the setting may be reset and the calibrator may return to ready-to- work state at the 1 V range.

Operation on the current and then to generate the set current value. If you do not adhere to this sequence of operations, you have to take into account the rest of surge current occurring right at the moment you terminate the load of value many times the highest setting on a given range.

## Note:

Operation of the processing system can be heard on the 10A DC and 1000 ranges ( 2 kHz tone).

Load termination for milivolt ranges is presented in fig.2.5.6.( armature between the output and feedback terminals enhances the error).

